Binary Search Trees

EECS 214, Fall 2018

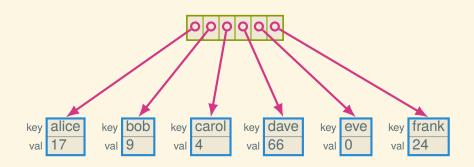
A data structure for dictionaries

There are several data structures that we can use to represent dictionaries:

- A list of keys-value pairs
- A hash table
- An array of key-value pairs
- A sorted array of key-value pairs

Let's consider the last one

A sorted array dictionary



Easy to lookup

```
Input: a dictionary array array and a key key
Output: a value, or nothing
start \leftarrow 0:
limit \leftarrow the length of array;
while start < limit do
    mid \leftarrow the average of start and limit;
    if key < array[mid].key then
         limit \leftarrow mid
    else if key > array[mid].key then
        start \leftarrow mid + 1
    else
        return array [mid].val
    end
end
return null
```

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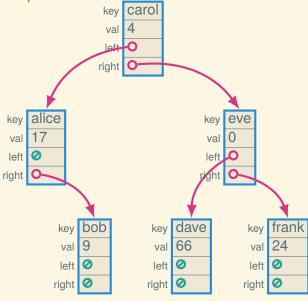
- Inserting into an array requires shifting elements out of the way
- There may be as many as *n* elements to move
- Hence insertion is $\mathcal{O}(n)$

Enter the BST

A binary search tree stores elements in order in a linked data structure

- In order means we can binary search
- Linked means we can easily insert new elements

BST example



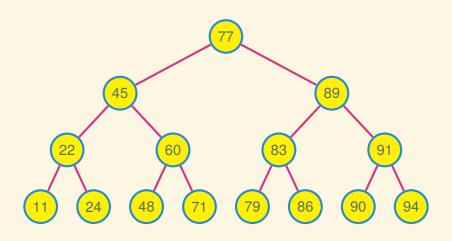
BST lookup algorithm

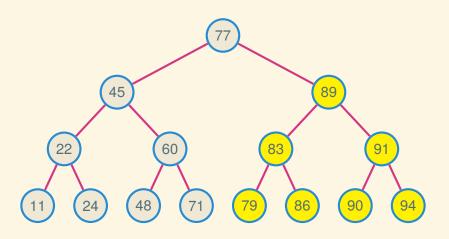
```
Input: a BST root root and a key key
Output: a value, or nothing
curr ← root:
while curr is not null do
   if key < curr.key then
       curr ← curr left
   else if key > curr.key then
        curr ← curr.right
   else
       return curr.val
   end
end
return null
```

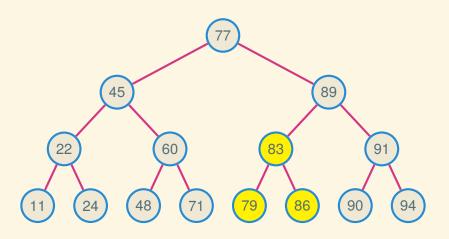
It's binary search, right?

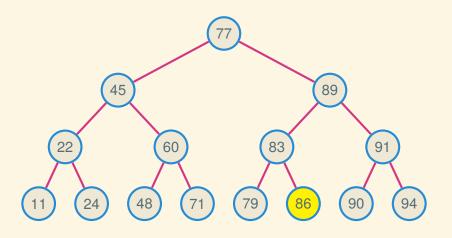
Binary search, again

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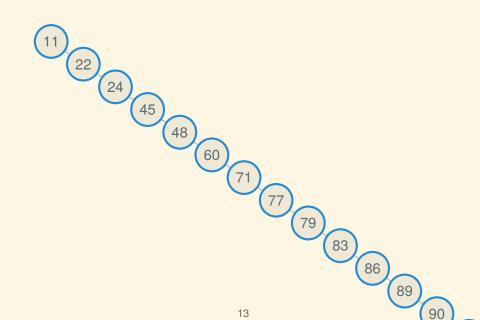








Complexity of BST lookup, take 2



BST insert algorithm (recursive)

```
Function BstInsert(node, key, value) is
   Output: the updated BST
   if node is null then
       return a new node with key, value, and null for both
         children
   else if key < node.key then
       node.left \leftarrow BstInsert(node.left, key, value);
       return node
   else if key > node.key then
       node.right \leftarrow BstInsert(node.right, key, value);
       return node
   else
       node.val = value;
       return node
   end
end
```

BST insert algorithm (with pointers)

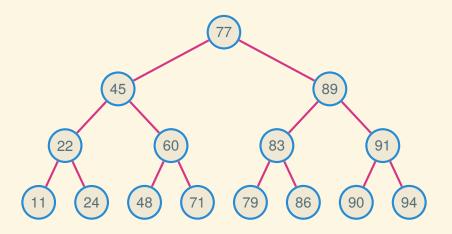
```
Input: a BST root root, a key key, and a value value
Output: the updated BST
curr \leftarrow the address of root:
while the value addressed by curr is not null do
   if key < curr.key then
       curr ← the address of curr.left
   else if key > curr.key then
       curr ← the address of curr.right
   else
       curr.val ← value:
       return
   end
end
newNode ←
 a new node with key, value, and null for both children;
the value addressed by curr ← newNode
```

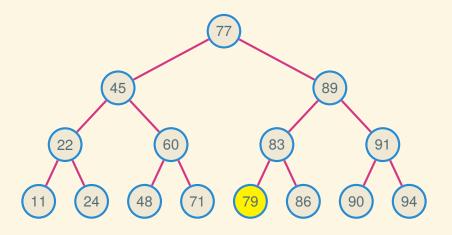
• First do a search — $\mathcal{O}(\log n)$

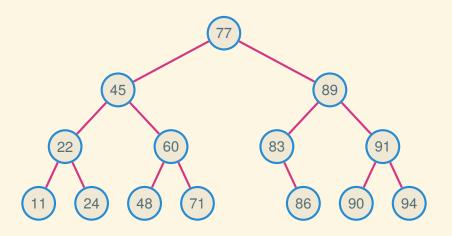
- First do a search $O(\log n)$
- If we find the key, replace the value $\mathcal{O}(1)$

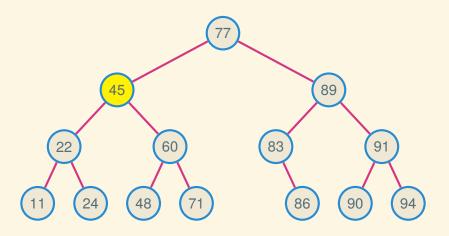
- First do a search $O(\log n)$
- If we find the key, replace the value $\mathcal{O}(1)$
- If not, add a new leaf where we hit bottom $\mathcal{O}(1)$

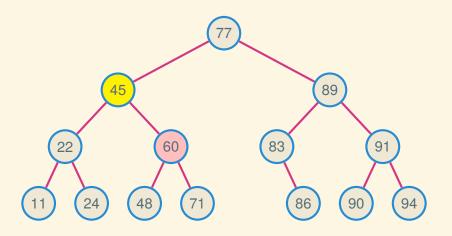
- First do a search $O(\log n)$
- If we find the key, replace the value $\mathcal{O}(1)$
- If not, add a new leaf where we hit bottom $\mathcal{O}(1)$
- Hence, $\mathcal{O}(\log n)$

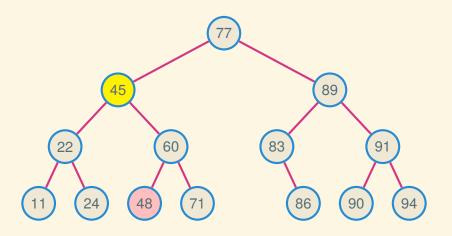


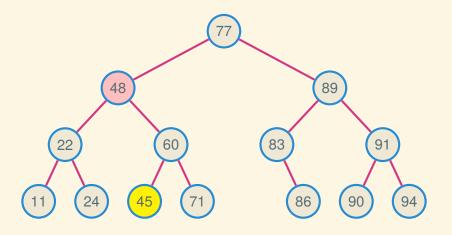


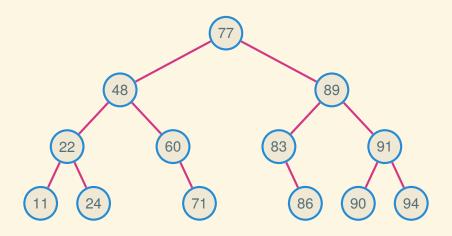


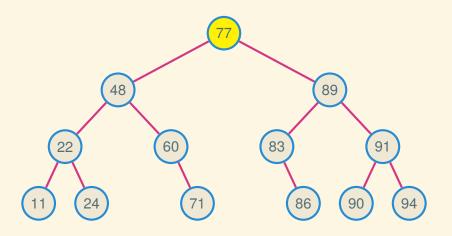


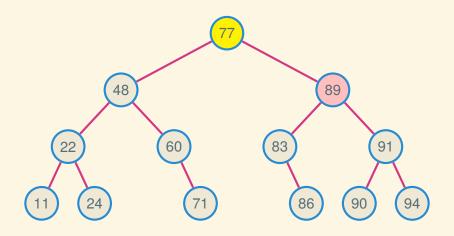


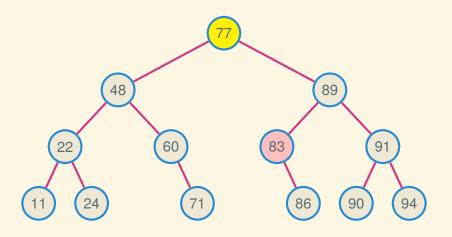


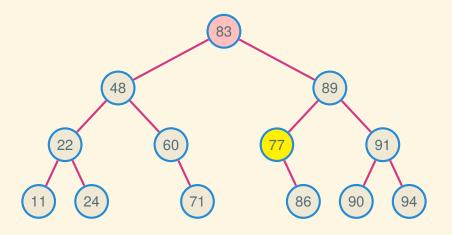


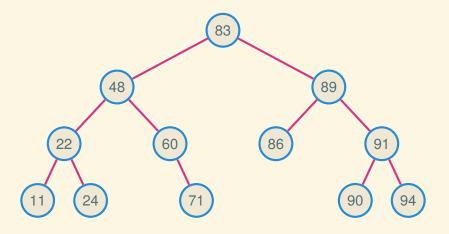












Next time: hashing and hash tables